CURSOR MOVEMENT ON OBJECT MOTION

An Application Development – II (Project) Report Submitted

In partial fulfilment of the requirement for the award of the degree of

Bachelor of Technology In

Computer Science and Engineering (Internet of Things)

By

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MALLA REDDY COLLEGE OF ENGINEERING AND TECHNOLOGY

(Autonomous Institution - UGC, Govt. of India)

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CERTIFICATE

This is to certify that this is the bonafide record of the project titled "CURSOR MOVEMENT ON OBJECT MOTION", submitted by A HARIKA (20N31A6905), KARNATI SRIKANTH (20N31A6925) and P AKHIL VIGNAN (20N31A6942) of B. Tech III YEAR – II Semester in the partial fulfilment of the requirements for the degree of Bachelor of Technology in Computer Science and Engineering (Internet of Things), Dept. of CSE (Emerging Technologies) during the year 2022-2023. The results embodied in this project report have not been submitted to any other university or institute for the award of any degree or diploma.

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DECLARATION

We hereby declare that the project entitled "CURSOR MOVEMENT ON OBJECT MOTION" submitted to Malla Reddy College of Engineering and Technology, affiliated to Jawaharlal Nehru Technological University Hyderabad (JNTUH) as part of III Year B. Tech – II Semester and for the partial fulfilment of the requirement for the award of Bachelor of Technology in Computer Science and Engineering (Internet of Things) is a result of original research work done by us.

It is further declared that the project report or any part thereof has not been previously submitted to any University or Institute for the award of degree or diploma.

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ABSTRACT

This project is a mouse simulation system which performs all the functions performed by your mouse corresponding to your hand movements and gestures. System will detect hand which will act as cursor. In this the camera captures your video and depending on your hand gestures, you can move the cursor and perform left click, right click, drag, select and scroll up and down. The predefined gestures make use of only two fingers marked numerically. The project is essentially a program which applies image processing, retrieves necessary data and implements it to the mouse interface of the computer according to predefined notions. The code is written on Python. Its uses of the cross-platform image processing module OpenCV and implements the mouse actions using Python specific library PyAutoGUI. The system can be broken down in three main components, which are - Hand Tracking, Gesture Recognition, Cursor Control. It aims to provide the user a better understanding of the system and to let them use alternate ways of interacting with the computer for a task. The project can be useful for various professional and non-professional presentations. It can also be used at home by users for recreational purposes like while watching movies or playing games.

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INTRODUCTION

The importance of computers is increasing constantly. Computer can be used for many purposes. We often use hardware devices such as mouse and keyboard to interact with the computers. In today's world, technologies are evolving day by day. One of the examples is that we use Bluetooth installed in the system without having any wired connections. Computer Vision-Based Mouse is a system to control the cursor of our computer without using any physical device even a mouse. Our system basically uses image processing, object detection and motion tracking to control the mouse activities such as its movement, left-click, right-click and double click. A machine learning project based on python libraries like mediapipe and opency. A virtual hand gesture mouse, that allows users to control a computer mouse using hand gestures instead of a physical mouse.

To develop this project, we will be using two functionalities like:

- Movement of cursor triggered by the hand movement.
- Click will be triggered based on the action of Index finger and Middle finger.

A hand landmark model is a machine learning model that is trained to identify and locate specific points or landmarks on a human hand in an image or video. These landmarks correspond to anatomical features of the hand such as the fingertips, knuckles, and wrist, and their precise locations can be used to track the movements and gestures of the hand.

➤ It performs features like:

- o Click or select files.
- o Drag and drop operation.
- o Increase or decrease volume.
- o Scroll pages, file or folders vertically
- Zoom in and out webpages.

1.1 PROBLEM DEFINITION

The system uses computer vision and motion tracking technology to interpret the movements of the user's hand and translate them into mouse commands. It can also be used in situations where a physical mouse is not available or practical, such as in virtual reality or augmented reality environments. A hand landmark model is a machine learning model that is trained to identify and locate specific points or landmarks on a human hand in an image or video. These landmarks correspond to anatomical features of the hand such as the fingertips, knuckles, and wrist, and their precise locations can be used to track the movements and gestures of the hand.

1.2 EXISTING SYSTEM

In the current scenario, the existing system has many flaws which make it inefficient to carry on with it. Here, the existing system uses an approach for controlling the mouse movement using colored objects like any RGB colors in front of the web cam for the movement of cursor. It consists of the simple mouse operation using the colored tips for detection which are captured by web-cam, hence colored fingers act as an object which the web-cam sense color like red, green, blue color to monitor the system. It performs the tasks like movement of the mouse and click events.

1.3 PROPOSED SYSTEM

In the proposed system, we have generated the code individually for different actionslike: Click or select file, drag and drop operation, Increase or decrease volume, scroll pages, file or folders vertically, zoom in and out webpages, there is no need of any RGB objects in the movement of cursor, it detects the hand as an object for the movement.				

SYSTEM REQUIREMENTS

2.1 Software Requirements:

- Operating system: Windows
- Coding Language: Python with modules like-
 - > Cv2 is used for video capturing.
 - Mediapipe is used for giving land mark for palm from 0-20.
 - > PyAutoGUI provides the ability to simulate mouse cursor moves and clicks.

2.2 Hardware Requirements:

- Monitor
- Web Cam

Programming Language:

• Python Programming

SYSTEM DESIGN

3.1 SOFTWARE

- Operating system: Windows
- Coding Language: Python with modules like-
 - > Cv2 is used for video capturing.
 - ➤ Mediapipe is used for giving land mark for palm from 0-20.
 - > Pyautogui provides the ability to simulate mouse cursor moves and clicks.

PYTHON PROGRAMMING LANGUAGE:

Python is a high-level, general-purpose programming language that is designed to be easy to read and write. It was first released in 1991 by Guido van Rossum and has since become one of the most popular programming languages in the world. Python's syntax emphasizes code readability, and it has a vast standard library and a large community of developers who have created many useful third-party libraries. Python can be used for a wide range of applications, including web development, data analysis, machine learning, scientific computing, and more. Additionally, it supports multiple programming paradigms, including procedural, object-oriented, and functional programming.

FEATURES OF PYTHON PROGRAMMING LANGUAGE:

• <u>Dynamic typing</u>: variable types are determined at runtime, which can make code easierto write and read.

- <u>Automatic memory management</u>: memory is managed by the interpreter, which freesdevelopers from having to manage memory explicitly.
- Strong support for data structures: Python provides built-in support for lists, dictionaries, and sets, which makes it easy to work with complex data.
- <u>Easy to learn and use</u>: Python's simple syntax and straightforward design make it anaccessible language for beginners and experienced programmers alike.

3.2 <u>Data Flow Diagrams / UML Diagrams</u>

3.2.1 Data Flow Diagram

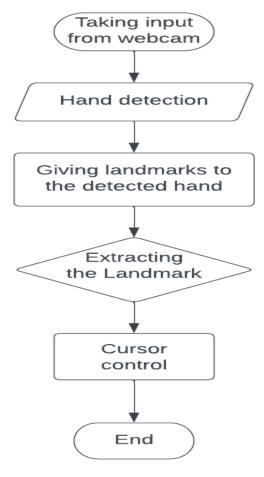


Fig 1: Data Flow Diagram

3.2.2 Use Case Diagram:

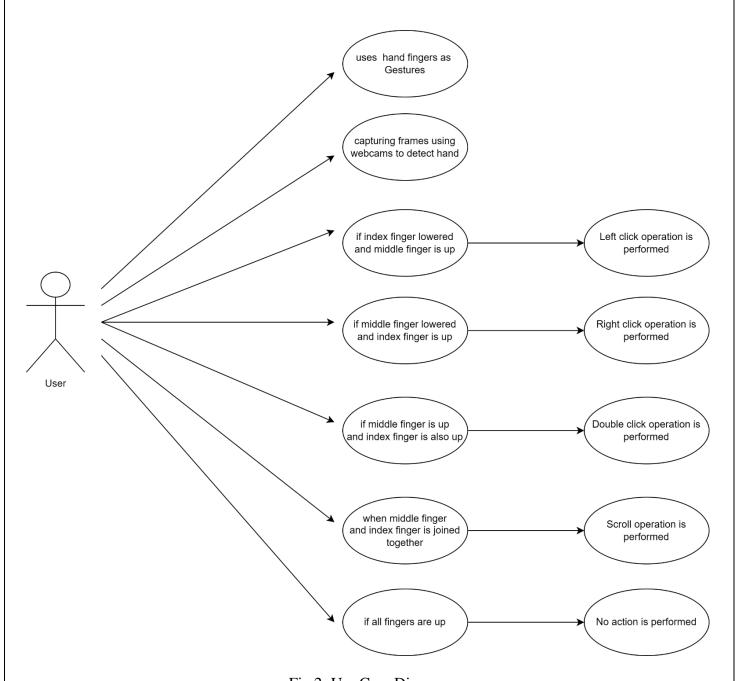


Fig 2: Use Case Diagram

3.3 System Architecture/ ER Diagram/ Sequential Diagram:

3.3.1 System Architecture

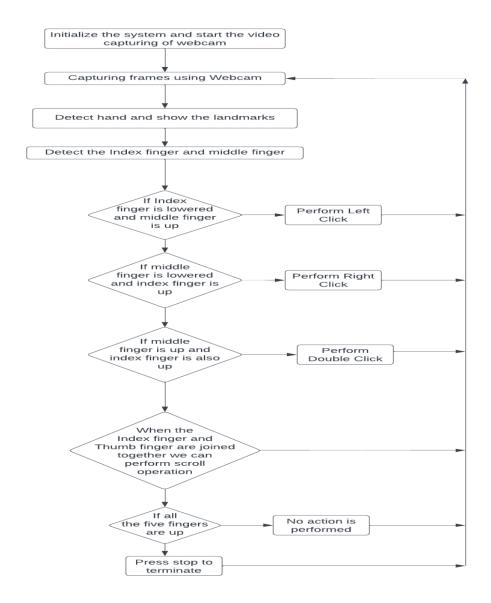


Fig 3: System Architecture

3.3.2 ER Diagram:

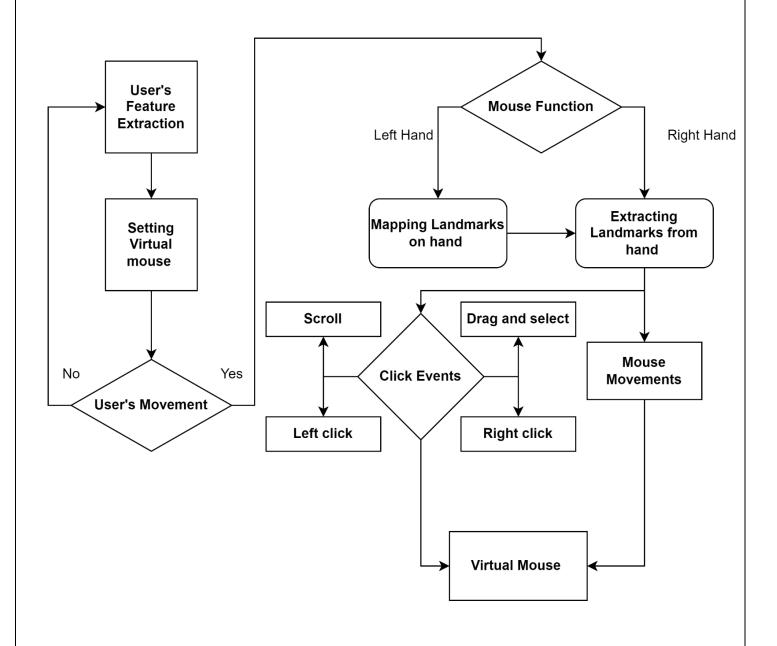


Fig 4:ER Diagram

3.3.3 Sequential Diagram:

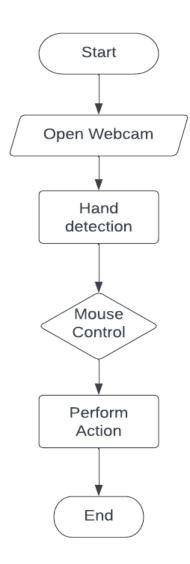


Fig 5: Sequential Diagram

SOFTWARE DEVELOPMENT LIFE CYCLE

4.1 SDLC:

SDLC stands for Software Development Life Cycle, which is a process used by software development teams to design, develop, test, and deploy software applications. The SDLC consists of several stages, including planning, analysis, design, implementation, testing, and maintenance.

4.2 PHASES OF SDLC:

A system development life cycle or SDLC is essentially a project management model. It defines different stages that are necessary to bring a project from its initial idea or conception all the way to deployment and later maintenance.

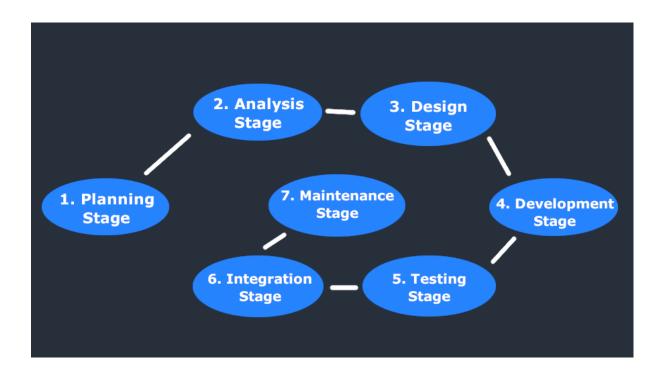


Fig 6: Phases of SDLC

7 Stages of the System Development Life Cycle:

There are seven primary stages of the modern system development life cycle. Here's a briefbreakdown:

- Planning Stage
- Feasibility or Requirements of Analysis Stage
- Design and Prototyping Stage
- Software Development Stage
- Software Testing Stage
- Implementation and Integration
- Operations and Maintenance Stage

Planning Stage:

Before we even begin with the planning stage, the best tip we can give you is to take time and acquire proper understanding of app development life cycle. The planning stage (also called the feasibility stage) is exactly what it sounds like: the phase inwhich developers will plan for the upcoming project. It helps to define the problem and scope of any existing systems, as well as determine the objectives for their new systems. By developing an effective outline for the upcoming development cycle, they'll theoretically catch problems before they affect development. And help to secure the funding and resources they need to make their plan happen. Perhaps most importantly, the planning stage sets the project schedule, which can be of key importance if development is for a commercial product that must be sent to market by a certaintime.

Analysis Stage:

The analysis stage includes gathering all the specific details required for a new system as wellas determining the first ideas for prototypes.

Developers may:

- Define any prototype system requirements
- Evaluate alternatives to existing prototypes
- Perform research and analysis to determine the needs of end-users

Furthermore, developers will often create a software requirement specification or SRS document. This includes all the specifications for software, hardware, and network requirements for the system they plan to build. This will prevent them from overdrawing funding or resources whenworking at the same place as other development teams.

Design Stage:

The design stage is a necessary precursor to the main developer stage. Developers will first outline the details for the overall application, alongside specific aspects, such as its:

- User interfaces
- System interfaces
- Network and network requirements
- Databases

They'll typically turn the SRS document they created into a more logical structure that can later be implemented in a programming language. Operation, training, and maintenance plans will all be drawn up so that developers know what they need to do throughout every stage of the cycle moving forward. Once complete, development managers will prepare a design document to be referenced throughout the next phases of the SDLC.

Development Stage:

The development stage is the part where developers actually write code and build the application according to the earlier design documents and outlined specifications. This is where Static Application Security Testing or SAST tools come into play. Product program code is built per the design document specifications. In theory, all of the priorplanning and outlined should make the actual development phase relatively straightforward. Developers will follow any coding guidelines as defined by the organization and utilizedifferent tools such as compilers, debuggers, and interpreters. Programming languages can include staples such as C++, PHP, and more. Developers willchoose the right programming code to use based on the project specifications and requirements.

<u>Testing Stage</u>:

Building software is not the end. Now it must be tested to make sure that there aren't any bugs and that the end-user experience will not negatively be affected at any point. During the testing stage, developers will go over their software with a fine-tooth comb, noting any bugs or defects that need to be tracked, fixed, and later retested. It's important that the software overall ends up meeting the quality standards that were previously defined in the SRS document. Depending on the skill of the developers, the complexity of the software, and the requirements for the end-user, testing can either be an extremely short phase or take a very long time.

<u>Implementation and Integration Stage</u>:

After testing, the overall design for the software will come together. Different modules or designs will be integrated into the primary source code through developer efforts, usually by leveraging training environments to detect further errors or defects. The information system will be integrated into its environment and eventually installed. Afterpassing this stage, the software is theoretically ready for market and may be provided to any end-users.

Maintenance Stage:

The SDLC doesn't end when software reaches the market. Developers must now move into a maintenance mode and begin practicing any activities required to handle issues reported by end-users. Furthermore, developers are responsible for implementing any changes that the software mightneed after deployment.

IMPLEMENTATION

The major code for implementation:

```
import cv2
import mediapipe as mp
import pyautogui
import math
from enum import IntEnum
from ctypes import cast, POINTER
from comtypes import CLSCTX_ALL
from pycaw.pycaw import AudioUtilities, IAudioEndpointVolume
from google.protobuf.json_format import MessageToDict
pyautogui.FAILSAFE = False
mp_drawing = mp.solutions.drawing_utils
mp_hands = mp.solutions.hands
class Gest(IntEnum):
    FIST = 0
PINKY = 1
    RING = 2
MID = 4
    LAST3 = 7
    INDEX = 8
   FIRST2 = 12
LAST4 = 15
    THUMB = 16
    PALM = 31
    V GEST = 33
    TWO FINGER CLOSED = 34
    PINCH MAJOR = 35
    PINCH_MINOR = 36
class HLabel(IntEnum):
    MINOR = 0
    MAJOR = 1
class HandRecog:
    def __init__(self, hand_label):
         self.finger = 0
         self.ori_gesture = Gest.PALM
         self.prev_gesture = Gest.PALM
```

```
self.prev_gesture = Gest.PALM
             self.frame_count = 0
             self.hand_result = None
             self.hand_label = hand_label
44
         def update_hand_result(self, hand_result):
             self.hand result = hand result
         def get signed dist(self, point):
             sign = -1
             if self.hand_result.landmark[point[0]].y < self.hand_result.landmark[point[1]].y:
            dist = (self.hand_result.landmark[point[0]].x - self.hand_result.landmark[point[1]].x) ** 2
            dist += (self.hand\_result.landmark[point[0]].y - self.hand\_result.landmark[point[1]].y) ** 2
            dist = math.sqrt(dist)
            return dist * sign
         def get_dist(self, point):
             dist = (self.hand_result.landmark[point[0]].x - self.hand_result.landmark[point[1]].x) ** 2
             dist += (self.hand_result.landmark[point[0]].y - self.hand_result.landmark[point[1]].y) ** 2
            dist = math.sqrt(dist)
            return dist
         def get_dz(self, point):
             return abs(self.hand result.landmark[point[0]].z - self.hand result.landmark[point[1]].z)
         def set_finger_state(self, dist1=None):
             if self.hand_result == None:
             points = [[8, 5, 0], [12, 9, 0], [16, 13, 0], [20, 17, 0]]
             self.finger = 0
             self.finger = self.finger | 0 # thumb
             for idx, point in enumerate(points):
                 dist = self.get_signed_dist(point[:2])
                 dist2 = self.get_signed_dist(point[1:])
                     ratio = round(dist / dist2, 1)
```

```
79
                      ratio = round(dist1 / 0.01, 1)
                  self.finger = self.finger << 1</pre>
                  if ratio > 0.5:
                      self.finger = self.finger | 1
          def get_gesture(self):
              if self.hand_result == None:
                  return Gest.PALM
              current_gesture = Gest.PALM
              if self.finger in [Gest.LAST3, Gest.LAST4] and self.get_dist([8, 4]) < 0.05:</pre>
                  if self.hand_label == HLabel.MINOR:
                      current_gesture = Gest.PINCH_MINOR
                      current_gesture = Gest.PINCH_MAJOR
              elif Gest.FIRST2 == self.finger:
94
                  point = [[8, 12], [5, 9]]
                  dist1 = self.get_dist(point[0])
                  dist2 = self.get_dist(point[1])
                  ratio = dist1 / dist2
                  if ratio > 1.7:
                      current_gesture = Gest.V_GEST
                       if self.get_dz([8, 12]) < 0.1:</pre>
                           current_gesture = Gest.TWO_FINGER_CLOSED
104
                           current_gesture = Gest.MID
                  current_gesture = self.finger
              if current_gesture == self.prev_gesture:
                  self.frame_count += 1
                  self.frame_count = 0
111
              self.prev_gesture = current_gesture
112
              if self.frame count > 4:
                  self.ori_gesture = current_gesture
113
114
              return self.ori_gesture
```

```
class Controller:
    tx_old = 0
   ty_old = 0
trial = True
    flag = False
    grabflag = False
    pinchmajorflag = False
    pinchminorflag = False
    pinchstartxcoord = None
    pinchstartycoord = None
    pinchdirectionflag = None
    prevpinchlv = 0
    pinchlv = 0
    framecount = 0
    prev_hand = None
    pinch_threshold = 0.3
    def getpinchylv(hand_result):
        dist = round((Controller.pinchstartycoord - hand_result.landmark[8].y) * 10, 1)
        return dist
    def getpinchxlv(hand_result):
        dist = round((hand_result.landmark[8].x - Controller.pinchstartxcoord) * 10, 1)
        return dist
    def changesystemvolume():
        devices = AudioUtilities.GetSpeakers()
        interface = devices.Activate(IAudioEndpointVolume._iid_, CLSCTX_ALL, None)
        volume = cast(interface, POINTER(IAudioEndpointVolume))
        currentVolumeLv = volume.GetMasterVolumeLevelScalar()
        currentVolumeLv += Controller.pinchlv / 50.0
        if currentVolumeLv > 1.0:
            currentVolumeLv = 1.0
        elif currentVolumeLv < 0.0:</pre>
            currentVolumeLv = 0.0
        volume.SetMasterVolumeLevelScalar(currentVolumeLv, None)
```

```
258
      class GestureController:
          gc_mode = 0
          cap = None
          CAM HEIGHT = None
          CAM_WIDTH = None
          hr_major = None # Right Hand by default
          hr_minor = None # Left hand by default
          dom_hand = True
          def __init__(self):
              GestureController.gc_mode = 1
              GestureController.cap = cv2.VideoCapture(0)
              GestureController.CAM_HEIGHT = GestureController.cap.get(cv2.CAP_PROP_FRAME_HEIGHT)
270
              GestureController.CAM_WIDTH = GestureController.cap.get(cv2.CAP_PROP_FRAME_WIDTH)
          def classify_hands(results):
274
              left, right = None, None
                  handedness_dict = MessageToDict(results.multi_handedness[0])
                  if handedness_dict['classification'][0]['label'] == 'Right':
                      right = results.multi_hand_landmarks[0]
                      left =
                             results.multi_hand_landmarks[0]
                  handedness dict = MessageToDict(results.multi handedness[1])
                  if handedness_dict['classification'][0]['label'] == 'Right':
                      right = results.multi_hand_landmarks[1]
                      left = results.multi hand landmarks[1]
              if GestureController.dom_hand == True:
                  GestureController.hr major =
                                               right
                  GestureController.hr_minor
                                               left
294
                  GestureController.hr_major =
                                               left
296
                  GestureController.hr minor = right
```

```
GestureController.hr_minor = right
        handmajor = HandRecog(HLabel.MAJOR)
handminor = HandRecog(HLabel.MINOR)
        with mp_hands.Hands(max_num_hands=2, min_detection_confidence=0.5, min_tracking_confidence=0.5) as hands:
while GestureController.cap.isOpened() and GestureController.gc_mode:
                 success, image = GestureController.cap.read()
                      print("Ignoring empty camera frame.")
                  image = cv2.cvtColor(cv2.flip(image, 1), cv2.COLOR_BGR2RGB)
                  image.flags.writeable = False
                  results = hands.process(image)
                  image.flags.writeable = True
                  image = cv2.cvtColor(image, cv2.COLOR_RGB2BGR)
                  if results.multi_hand_landmarks:
                      GestureController.classify_hands(results)
                      handmajor.update_hand_result(GestureController.hr_major)
                      handminor.update_hand_result(GestureController.hr_minor)
                      handmajor.set_finger_state()
handminor.set_finger_state()
                      gest_name = handminor.get_gesture()
                      if gest_name == Gest.PINCH_MINOR:
                          Controller.handle_controls(gest_name, handminor.hand_result)
                          gest_name = handmajor.get_gesture()
                           Controller.handle_controls(gest_name, handmajor.hand_result)
                      for hand landmarks in results.multi hand landmarks:
                          mp_drawing.draw_landmarks(image, hand_landmarks, mp_hands.HAND_CONNECTIONS)
                      Controller.prev_hand = None
                  cv2.imshow('Virtual Mouse', image)
                  if cv2.waitKey(5) & 0xFF == 13:
        GestureController.cap.release()
         cv2.destroyAllWindows()
gc1 = GestureController()
gc1.start()
```

CHAPTER 6 TESTING

6.1 TEST CASE FOR RIGHT CLICK:

```
ad2.py
                 Controller.framecount += 1
                 Controller.prevpinchlv = lvy
                 Controller.framecount = 0
        elif abs(lvx) > Controller.pinch_threshold:
            Controller.pinchdirectionflag = True
if abs(Controller.prevpinchlv - lvx) < Controller.pinch_threshold:</pre>
                 Controller.framecount += 1
                 Controller.prevpinchlv = lvx
                 Controller.framecount = 0
    def handle_controls(gesture, hand_result):
        x, y = None, None
         if gesture != Gest.PALM:
            x, y = Controller.get_position(hand_result)
        if gesture != Gest.FIST and Controller.grabflag:
            Controller.grabflag = False
                                                                                 Show Unsaved Changes...
            pyautogui.mouseUp(button="left")
        if gesture != Gest.PINCH_MAJOR and Controller.pinchmajorflag:
                                                                                 Cut
            Controller.pinchmajorflag = False
                                                                                 Сору
        if gesture != Gest.PINCH_MINOR and Controller.pinchminorflag:
                                                                                 Paste
            Controller.pinchminorflag = False
         if gesture == Gest.V_GEST:
                                                                                 Select All
             Controller.flag = True
            pyautogui.moveTo(x, y, duration=0.1)
                                                                                 Open Containing Folder...
        elif gesture ==
                         Gest.FIST:
                                                                                 Copy File Path
             if not Controller.grabflag:
                                                                                 Reveal in Side Bar
                 Controller.grabflag = True
                 pyautogui.mouseDown(button="left")
             pyautogui.moveTo(x, y, duration=0.1)
        elif gesture
                         Gest.MID and Controller.flag:
            pyautogui.click()
```

Fig 7: Test case for right click

6.2 TEST CASE FOR SELECTION:

```
rile cuit selection rina view doto tools Project Preferences melp
      ad2.py
                   if abs(Controller.prevpinchlv - lvy) < Controller.pinch_threshold:</pre>
        Controller.framecount += 1
             Controller.prevpinchlv = lvy
 208
                       Controller.framecount
                   f abs(lvx) >> Controller.pinch_threshold:
                Controller.pinchdirectionflag = True
 212
                if abs(Controller.prevpinchlv - lvx) < Controller.pinch_threshold:</pre>
                    Controller.framecount += 1
                       Controller.prevpinchlv = lvx
                       Controller.framecount = 0
        def handle_controls(gesture, hand_result):
              x, y = None, None
               if gesture != Gest.PALM:
                   x, y = Controller.get_position(hand_result)
               if gesture != Gest.FIST and Controller.grabflag:
                   Controller.grabflag = False
                   pyautogui.mouseUp(button="left")
               if gesture != Gest.PINCH_MAJOR and Controller.pinchmajorflag:
                   Controller.pinchmajorflag = False
               if gesture != Gest.PINCH_MINOR and Controller.pinchminorflag:
                   Controller.pinchminorflag = False
               if gesture == Gest.V_GEST:
 230
                   Controller.flag = True
                   pyautogui.moveTo(x, y, duration=0.1)
               elif gesture =
                              Gest.FIST:
                   if not Controller.grabflag:
 234
                       Controller.grabflag = True
                       pyautogui.mouseDown(button="left")
                   pyautogui.moveTo(x, y, duration=0.1)
                             Gest.MID and Controller.flag:
```

Fig 8: Test case for selection

6.3 TEST CASE FOR DETECTION:

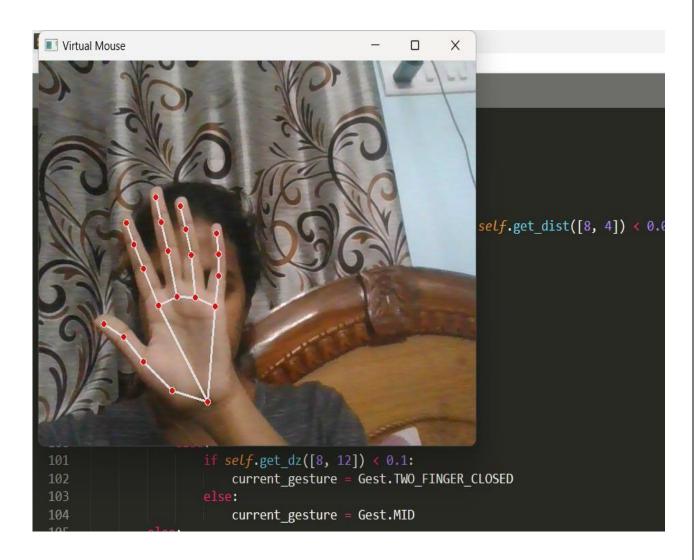


Fig 9: Test case for detection

6.4 TEST CASE FOR OPENING DIALOGUE BOX:

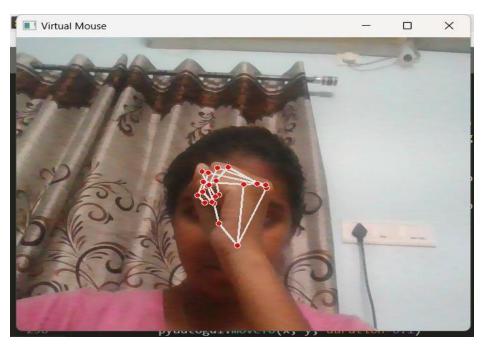


Fig 10: Test case for opening dialogue box

6.5 OVERALL TEST CASES:

S No.	Functional Test Cases	Type-Negative or positive test case
1	Verify weather user can see the video capturing dialog box.	Positive
2	Verify weather web cam detects the hand.	Positive
3	Verify weather left click operation is preformed.	Positive
4	Verify weather right click operation is performed.	Positive
5	Verify weather any operation is performed when all fingers are up.	Negative
6	Verify weather scroll operation is performed.	Positive

Fig 11: Overall test cases

CONCLUSION AND FUTURE SCOPE

7.1 CONCLUSION

- In this project, we made attempt to effectively introduce the concept of replacement of the physical mouse.
- We then described the proposed system and explained the features implemented by our proposed system.
- The proposed system architecture will completely change the way people would use the computer system.
- A few techniques had to be implemented because accuracy and efficiency play an important role in making the program.

7.2 FUTURE SCOPE

- With this gesture recognition system, we can use computers without any help from physical devices such as mouse.
- This technology can make work easy as just one big screen can be used by researchers to do all the work.

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